



SPIRE Photometer Map Making

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on behalf of the SPIRE ICC



- **Baseline Removers:**
 - Destriper (**minimizing stripes iteratively, pipeline default**)
 - Median baseline remover
 - Polynomial baseline remover
- **Mapmakers:**
 - Naïve Mapper (**a simple mapper, used in Destriper**)
 - MADMapper (**more complicated, but not better**)



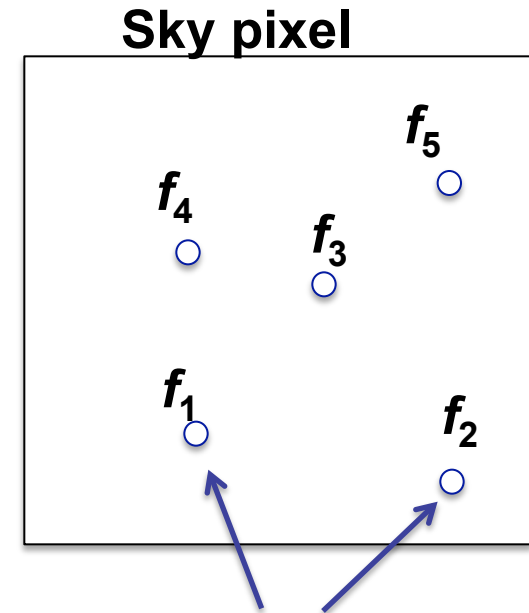
Two options:

(1) **No weighting:** Flux of a sky pixel is the **simple average** of all signal samplings (by all detectors) in the pixel:

$$f_{pixel} = \frac{\sum_i^n f_i}{n}, \quad error_{pixel} = \sqrt{\frac{\sum_i^n (f_i - f_{pixel})^2}{n(n-1)}}$$

(2) **Inverse variance (of instrument noise) weighted:** Flux of a sky pixel is the **inverse variance weighted mean** of all signal samplings in the pixel, the variance is calculated using the white noise of the detector with which a given sampling is taken:

$$f_{pixel} = \frac{\sum_i^n f_i / \sigma_i^2}{\sum_i^n 1 / \sigma_i^2}, \quad error_{pixel} = \sqrt{\frac{\sum_i^n (f_i - f_{pixel})^2 / \sigma_i^4}{\left(\sum_i^n 1 / \sigma_i^2\right)^2 - \sum_i^n 1 / \sigma_i^4}}$$

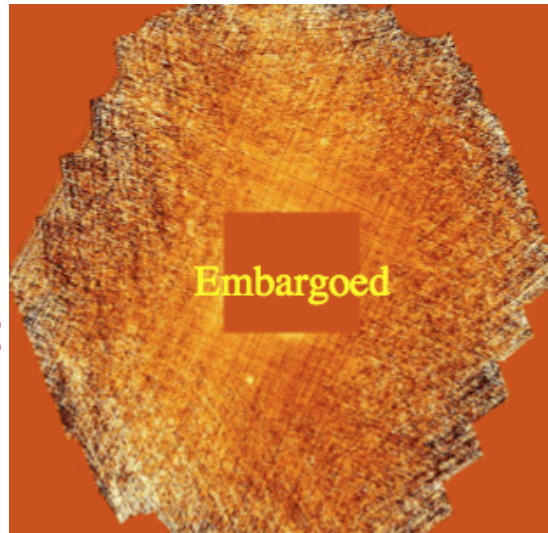


signal samplings



- A mapper originally developed for the CMB measurements (MAD: Microwave Anisotropy Dataset).
- The algorithm is FFT based.
- Strength: Minimize stripes due to uncorrelated detector drifts (“1/f noise”).

Example
(taken from
an earlier
talk of
PACS team):
Naïve map
of a PACS
observation



MADmap
of the same
observation



- Weakness: ringing effect (in the time domain) at any places the timelines have sharp changes (bright sources, edges of scans, etc.)

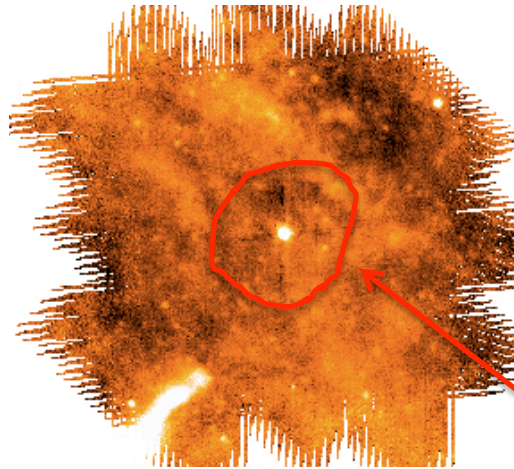


MADMapper:
*FFT based, minimize
uncorrelated 1/f noise*

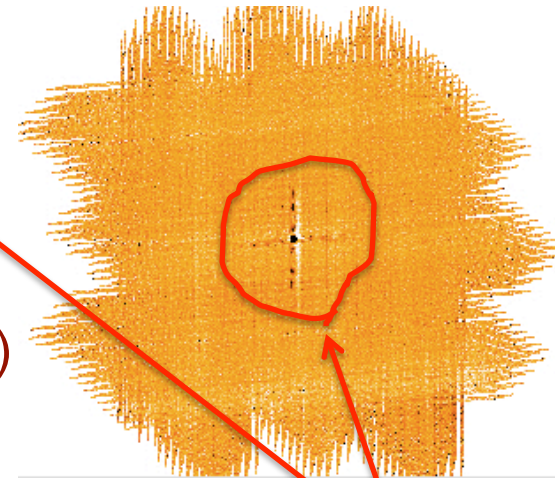
- `mapPlw=madScanMapper(level1, array="PLW")`

NaïveMapper:
simple average

- `mapPlw=naiveScanMapper(level1, array="PLW")`



Diff. map:

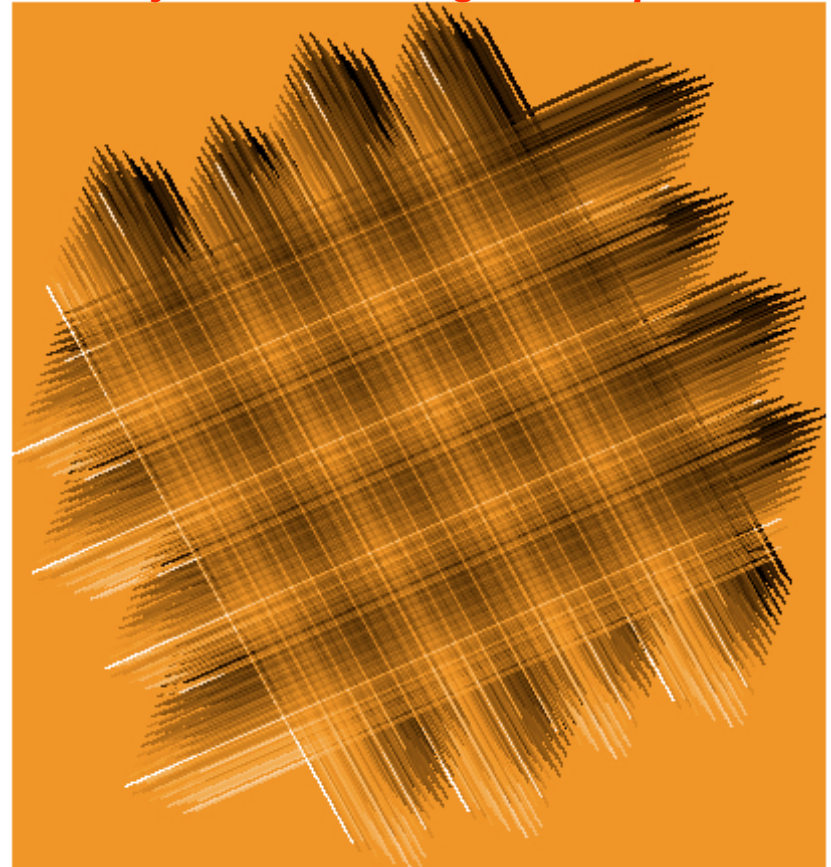


- MADmap has **shadows** around the central bright source, **due to ringing!!**
- MADMap does not improve over the simple naïve map: **weak uncorr. 1/f in SPIRE!!**



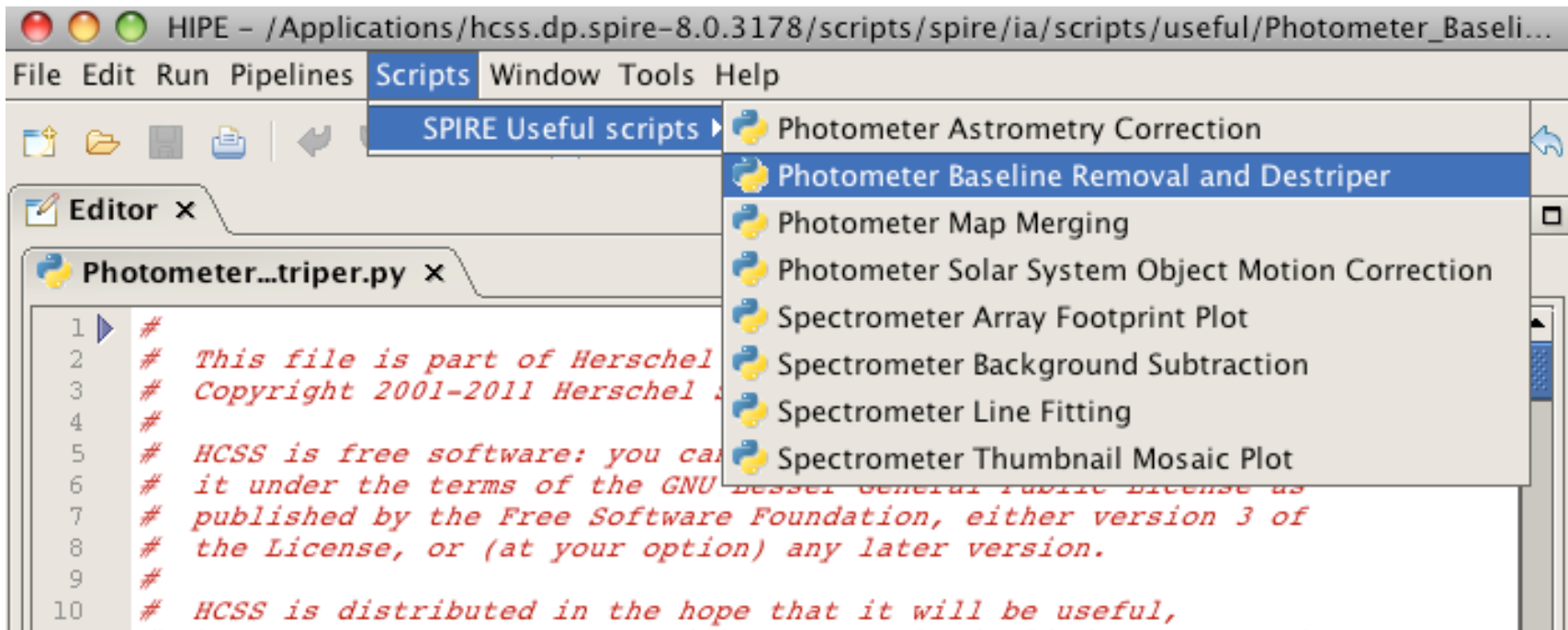
example: PSW map without baseline removal
you see nothing but stripes

- stripes: offsets of individual detector channels on the order of ~ 0.1 Jy/beam. (mainly caused by errors of Temperature Drift Correction).





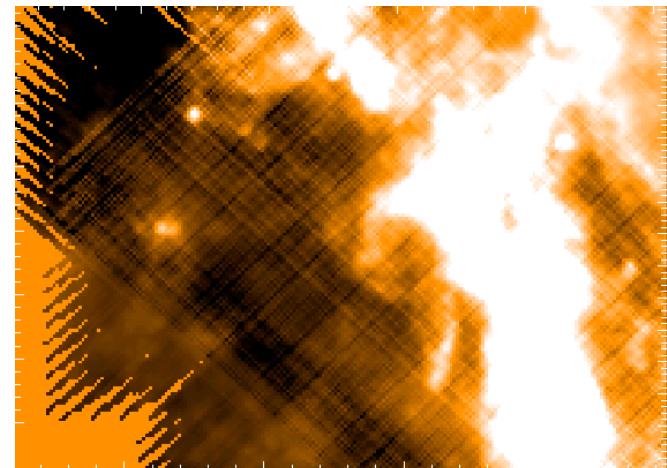
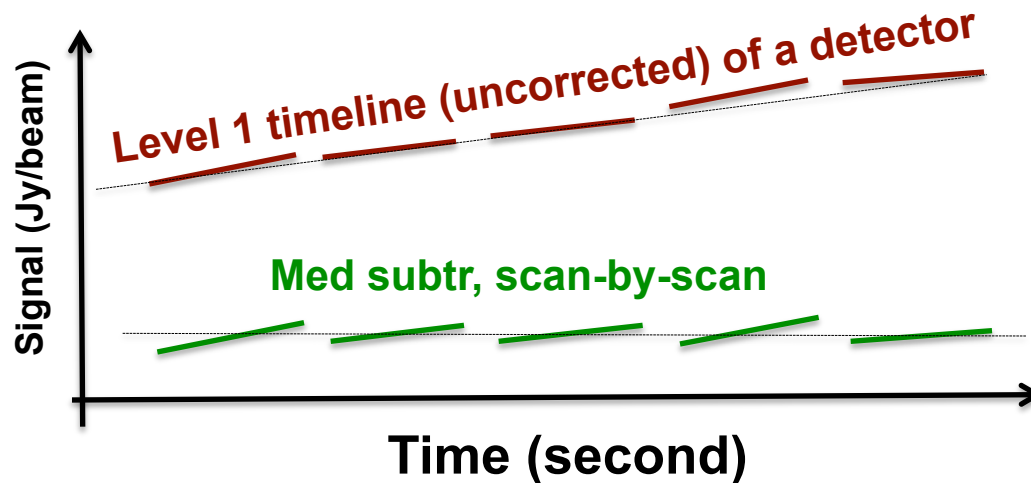
- 3 Baseline Removers:
 - Median baseline remover.
 - Polynomial baseline remover.
 - Destriper (**pipeline default**).





Module name: `baselineRemovalMedian`

1. Subtract the median scan-by-scan and detector-by-detector (default).
2. Subtract the median of each timeline detector-by-detector.

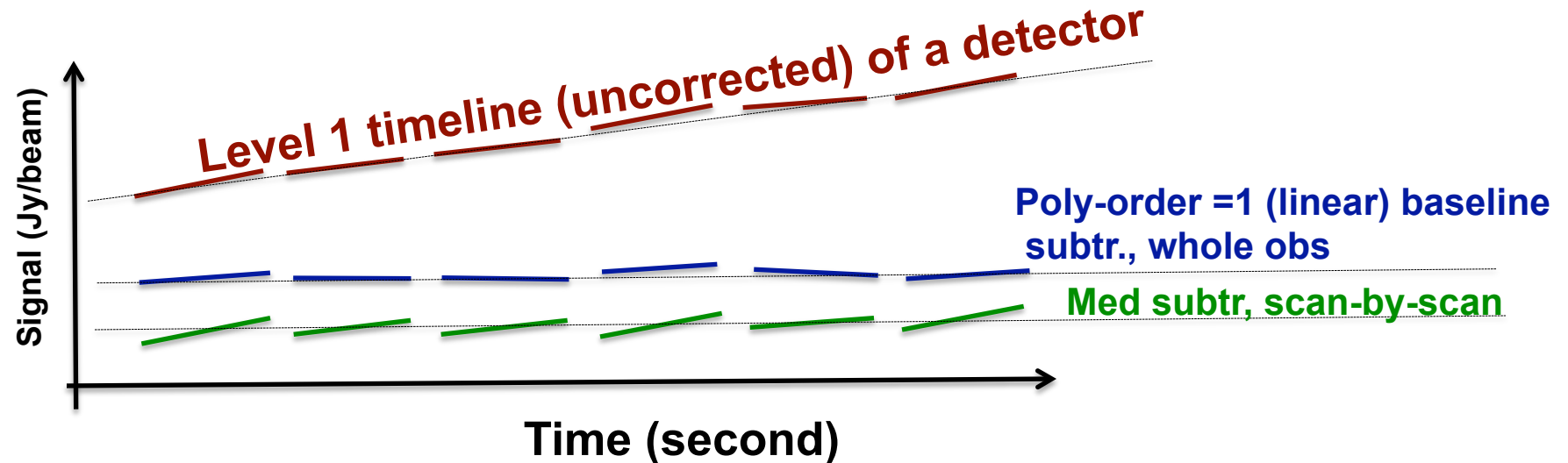


- **Strength:** simple (you know what you are doing).
- **Weakness:**
 - residual drifts (as shown in the illustration);
 - over subtraction when there is extended emission.



Module name: baselineRemovalPolynomial

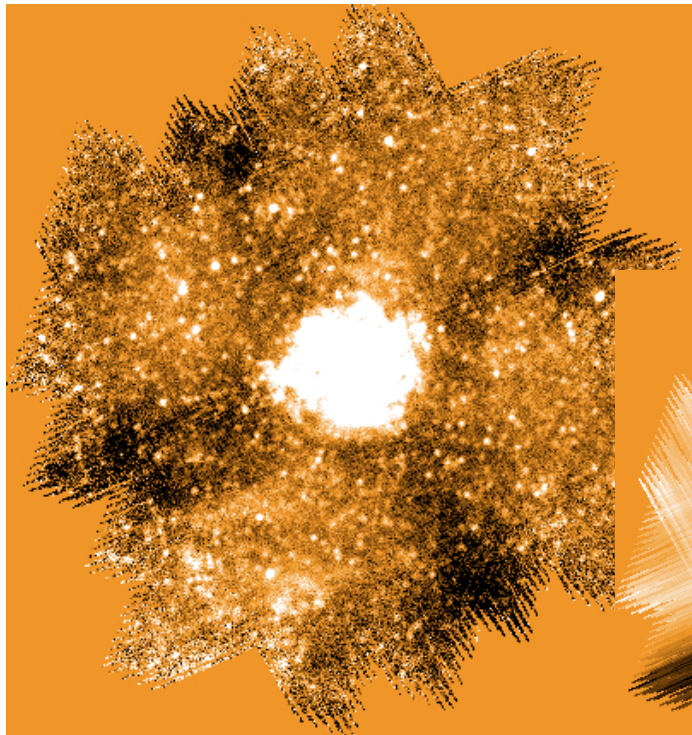
1. Subtract a polynomial baseline scan-by-scan and detector-by-detector.
2. Subtract a polynomial baseline of each timeline detector-by-detector.



- **Strength:** more flexible than median removal (often means less residual drifts).
- **Weakness (compare to median removal):**
 - more severe over-subtraction when the polynomial order is high.



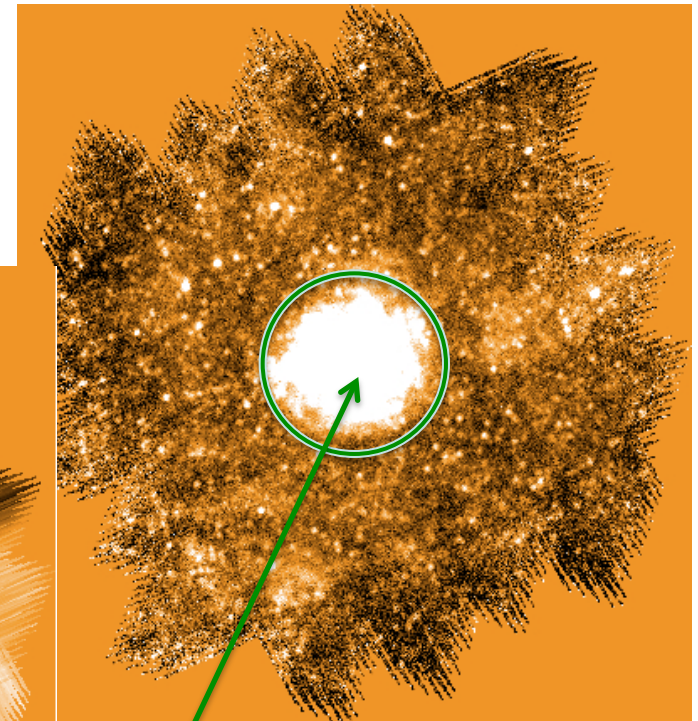
ROI (available for both median & polynomial baseline removers):
Excluding bright regions from baseline estimate to minimize the over-subtraction.



Median baseline removal without ROI mask.

An example for median remover

diff. map



Data inside this ROI are masked & excluded from baseline removal.



- **Destriper (pipeline default)**

- Minimize map stripes by adjusting the baseline subtraction (median or polynomial) iteratively using the naïve mapper.

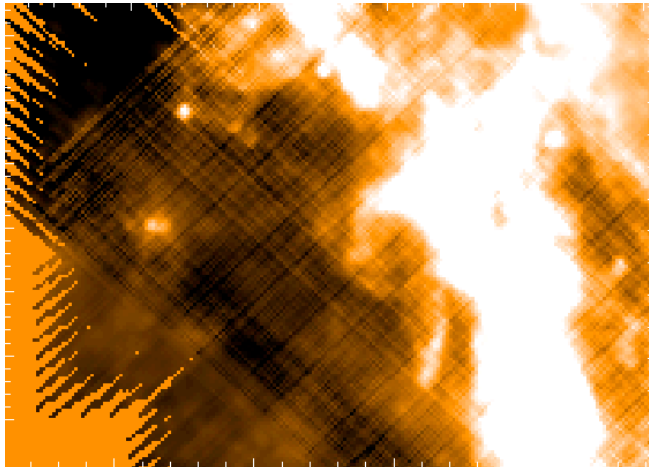
- **Strength:**

- make better maps in general (no significant over-subtraction);
- the only SPIRE baseline remover in HIPE for structured emission regions;
- can do the 2nd order deglitching (HIPE 9.1).

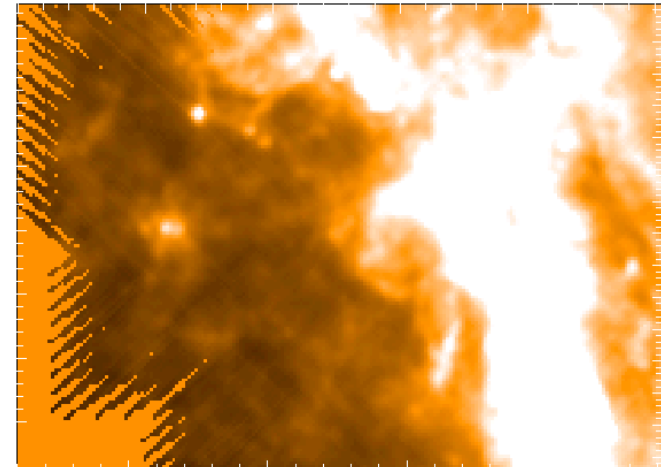
- **Weakness:**

- longer computation time, higher demand on RAM.

**Median
Baseline
Remover:**

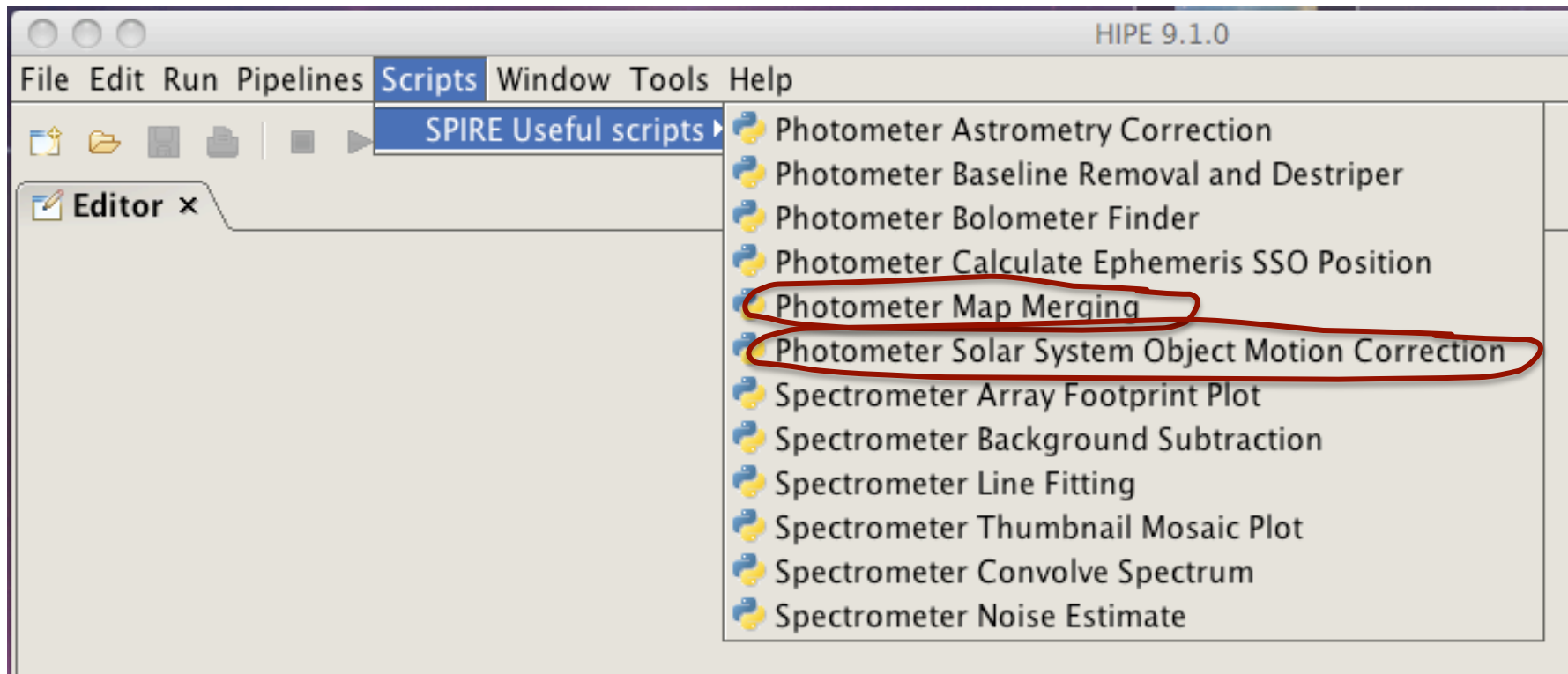


Destriper:





- **Map Merging**: Make maps using timelines of more than 1 observations (particularly useful for parallel mode observations with cross-scans).
- **Solar System Object Motion Correction**: Correct the proper motion of solar system objects (causing blurred images) before the mapmaking.





Summary

- As default, the pipeline makes map using the destriper, which minimizes the stripes due to baseline-offsets iteratively.
- In the reprocessing, if the map does not have much structure, one can opt to use naivemapper + baseline remover (median of polynomial, with or without ROI masking) to save time and RAM.
- We **do not** recommend to use MADMapper for SPIRE photometer maps.